




Canadian Railway Ground Hazard Research Program: Applications of remote sensing techniques for managing rock slope instability

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27 October, 2017




Canadian Railway Ground Hazard Research Program (RGHRP) - Overview

Program Objectives:
 To develop risk management solutions to improve safety and reduce losses from railway ground hazards.
 To meet the requirements for due diligence and standard-of-care under the Railway Safety Act, specifically Safety Management Systems.
 To provide solutions such as:

- application of new methodologies for assessing hazards,
- development and refinement of new monitoring & detection technologies, and
- improvements to existing systems.



RGHRP Motivation



Exposure is heightened by:

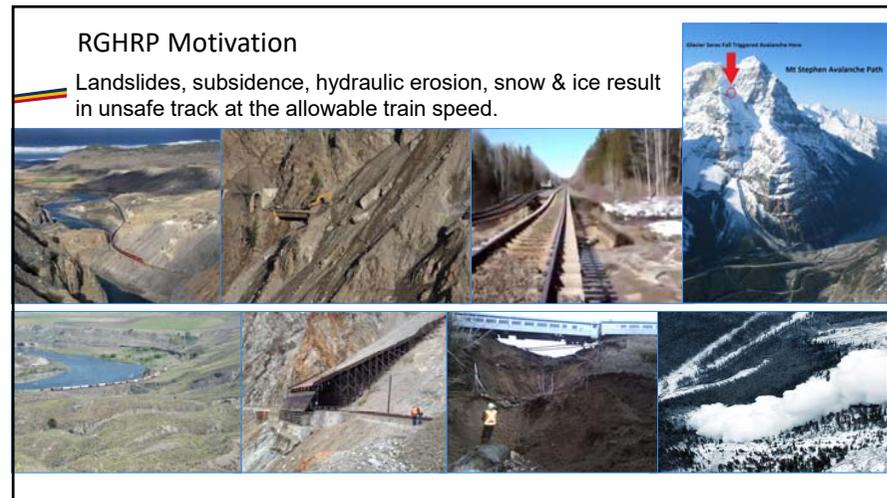
- diverse physiographic regions,
- soil and rock conditions,
- extensive and deep ground freezing,
- active geomorphic processes and climate extremes.

Rail Mainlines

- Canadian National
- Canadian Pacific
- Other Railways
- CN - US Track Rights
- CP - US Track Rights

RGHRP Motivation

Landslides, subsidence, hydraulic erosion, snow & ice result in unsafe track at the allowable train speed.



Elster Snow Fall Triggered Avalanche Here
 Mt. Stephen Avalanche Path

RGHRP Motivation



Railways are exposed to a wider variety and higher frequency of ground hazards, and have a higher exposure because of curvature and grade limitations. RESULT! Complex and uncertain ground hazards present a significant safety and operating risk to Canadian railways.



Project Team Leaders





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RGHRP contributions



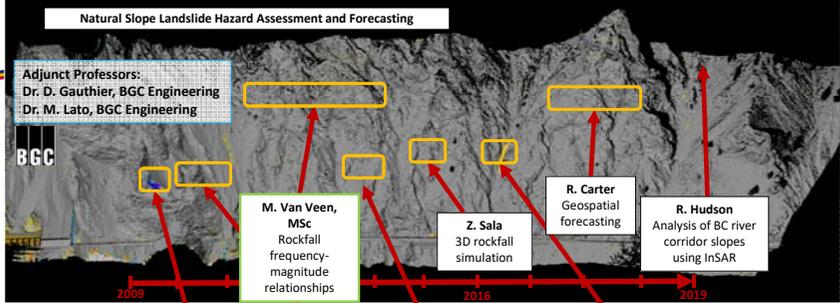
- Assessment and adoption of technologies for instrumentation, in collaboration with vendors and research teams – AccelArray, Geocubes, Microseismic, GPR, Acoustic waveguide, Resistivity, LiDAR, photogrammetry, UAV.
- Instrumentation installation and interpretation, and numerical simulation of complex mass movements, considering groundwater and geological models.
- Risk based assessment of ground hazards, including incident database development and analysis, probabilistic forecasting, evaluation of frequency / magnitude concepts, consideration of triggering activities.
- Development of practical guidelines for railway operation teams.
- Collaboration, training and information dissemination.



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Natural Slope Landslide Hazard Assessment and Forecasting



Adjunct Professors:
 Dr. D. Gauthier, BGC Engineering
 Dr. M. Lato, BGC Engineering

BGC

2009 2016 2019

- D. Gauthier, PDF - Applications of Photogrammetry
M. Lato, Ph.D. - Applications of LiDAR
- R. Kromer, PhD - Rock block deformation and forecasting
- M. Ondercin, MSc - 3D rockfall modelling
- E. Rowe, MSc - Rock block deformation and structure
- A. Graham - Weather influences on failures
- D. Bonneau - Debris flow analysis
- Natural slope rating system
- M. Van Veen, MSc - Rockfall frequency-magnitude relationships
- Z. Sala - 3D rockfall simulation
- R. Carter - Geospatial forecasting
- R. Hudson - Analysis of BC river corridor slopes using InSAR

Undergraduate Student Design Teams
 -3D Hazard mapping
 -3D Risk Assessment
 -Cost-Benefit Mitigation Analysis

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Linear infrastructure adjacent to rock slopes

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Linear infrastructure adjacent to rock slopes

Photo: courtesy of Tom Edwards

Rockfall event mitigation - Railways

Rock sheds

Slide detector fences and Ditches

Tunnels

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Managing rock slope instability

- For large, natural slopes:
 - How do we identify which features may generate failing rocks, next?
 - How do we observe and measure the potential source zones / failure volume?
 - Can we forecast potential failure?
 - Once we have identified a potential source zone, what is the risk to infrastructure?

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Case Study Site – White Canyon, British Columbia



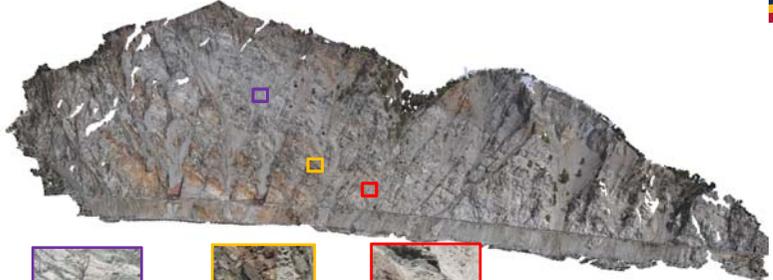


White Canyon, British Columbia

Legend

- Rock Street
- Tunnel
- Mill Pond
- Geophone Rockfall Data
- City Wall line

White Canyon Study Site

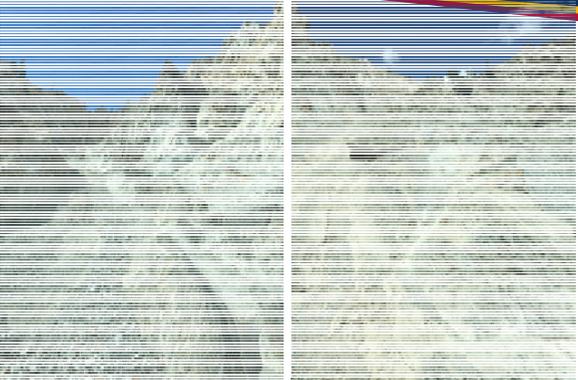


100 m

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Quartzofeldspathic Gneiss Dioritic Intrusions Tonalite Dykes

White Canyon Study Site

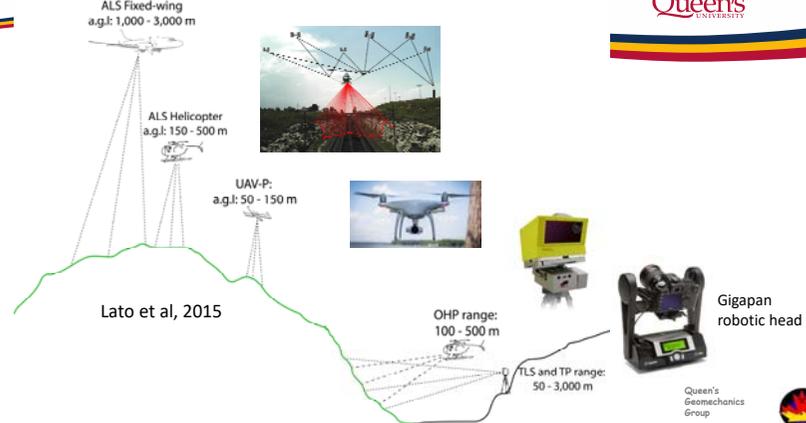


Active rockfall zone. Difficult to assess and monitor:

- Source of rockfalls, and
- Volume of debris in source zones.

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Remote Sensing techniques



Lato et al, 2015

ALS Fixed-wing a.g.l: 1,000 - 3,000 m

ALS Helicopter a.g.l: 150 - 500 m

UAV-P: a.g.l: 50 - 150 m

OHP range: 100 - 500 m

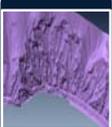
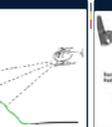
TLS and TP range: 50 - 3,000 m

Gigapan robotic head

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Overview of Methods Deployed at White Canyon



						
Terrestrial Laser Scanning (TLS) [2012 – Present]	Aerial Laser Scanning (ALS) [Fall 2014; Fall 2015]	GigaPan Imaging [2014 – Present]	Terrestrial Photogrammetry [2014 – Present]	UAV Photogrammetry [August 2016]	Helicopter Photogrammetry [October 2016]	InSAR [March 2014 – June 2015]

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GigaPan Imaging





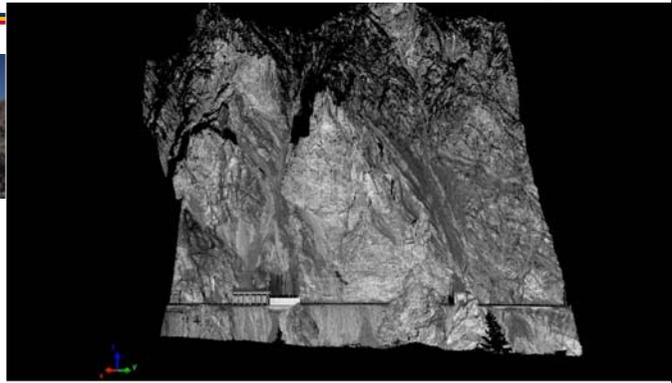

Gigapan example 



van Veen et al, 2015, 2016 & 2017

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LiDAR Point Cloud


Ryan Kromer

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Available TLS Data



Year	January	February	March	April	May	June	July	August	September	October	November	December
2012												
2013												
2014												
2015												
2016												
2017												



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Steps to produce a Change Detection Map, between sequential scans

Align scan boxes, then ICP alignment

Generate Mesh of Point Cloud

Shortest Distance between Meshes

Visualization of the results

Ryan Kromer and Megan van Veen

Ashcroft Mile 109.4

Comparison Dates: 2017-04-08 to 2017-05-23

Alex Graham

Change detection from 3-D models

Feature observation from GigaPan

5.8 m³ (in total)

Comparison – 5 month period

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Occlusions in Terrestrial Laser Scanning

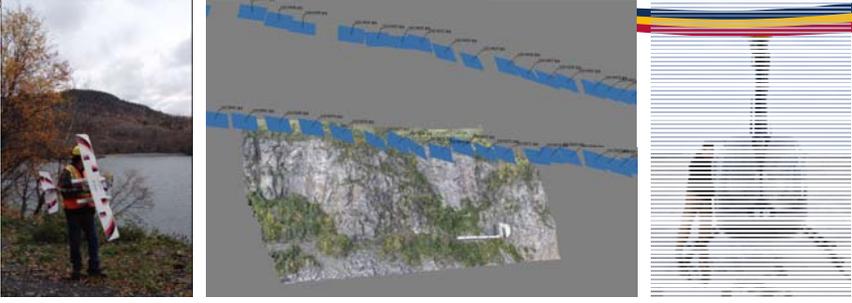
Limited occlusion areas

(van Veen, 2016)

50 m

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Photogrammetry



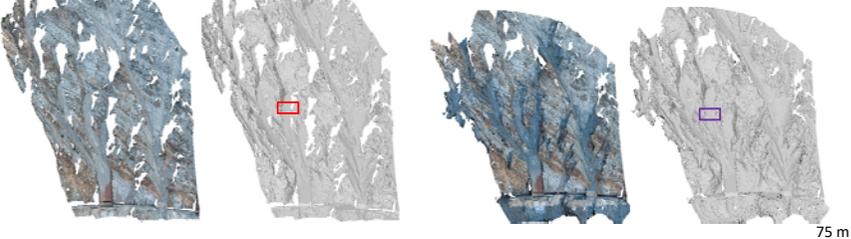
Photogrammetry revolutionized by Structure From Motion processing – Agisoft PhotoScan

Gauthier et al, 2015

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Photogrammetry



Terrestrial Terrestrial + UAV

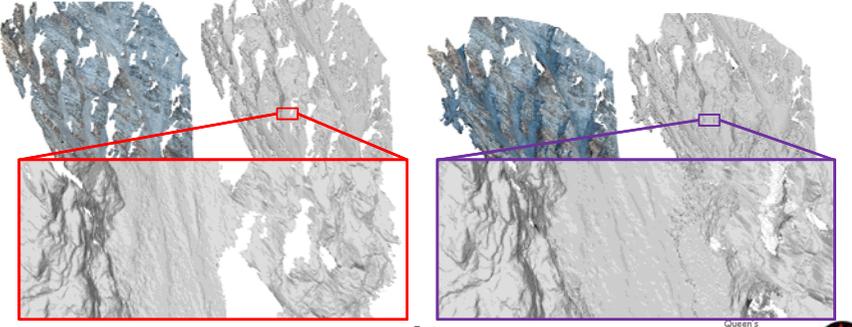
75 m

Connor Meeks and David Bonneau

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Photogrammetry



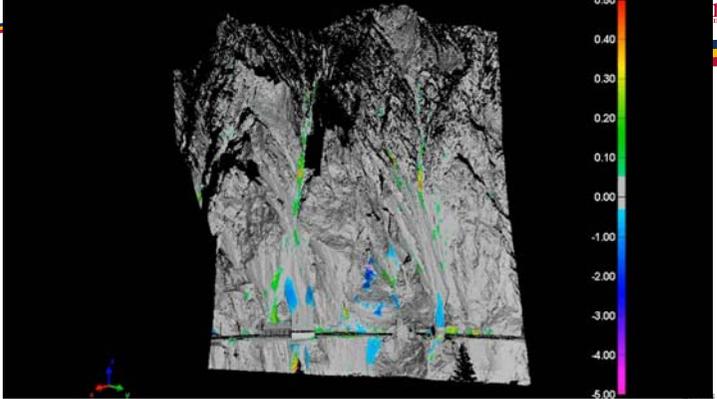
5 m

Connor Meeks and David Bonneau

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Active rock slope – LiDAR change detection

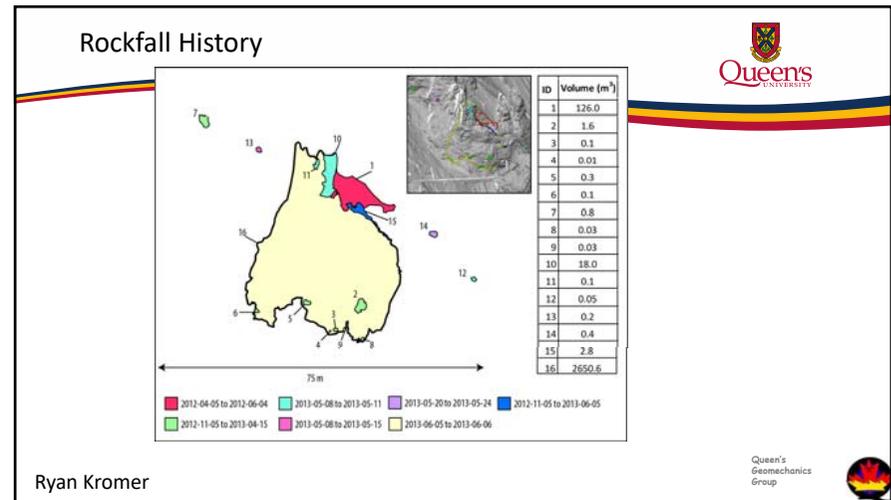
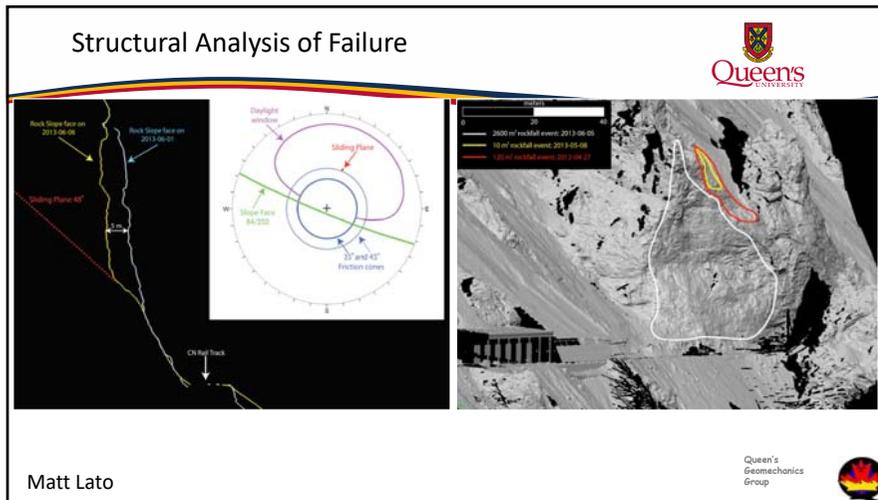
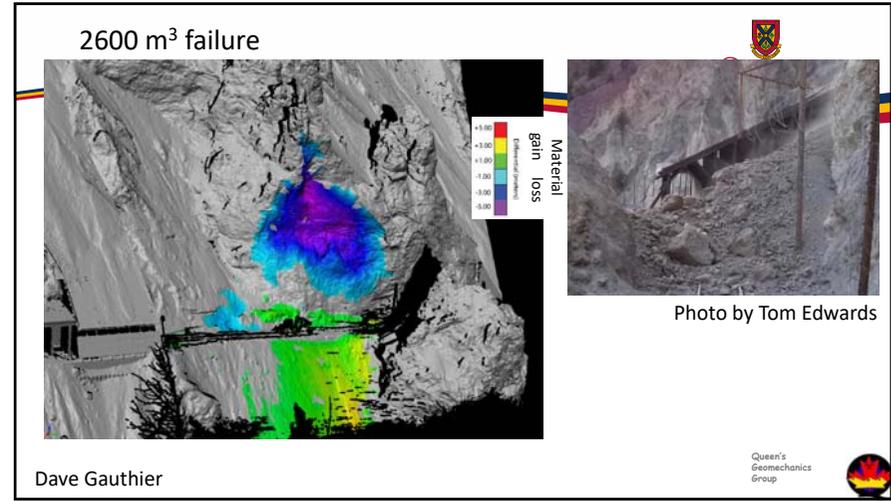
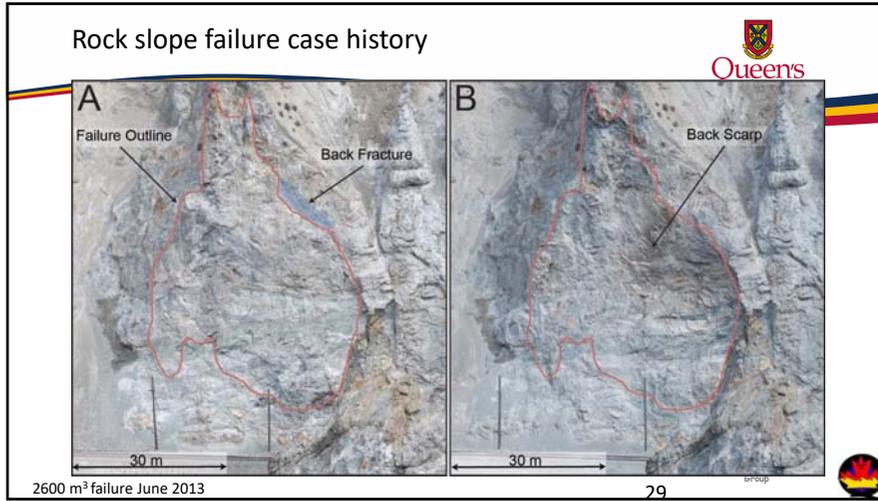


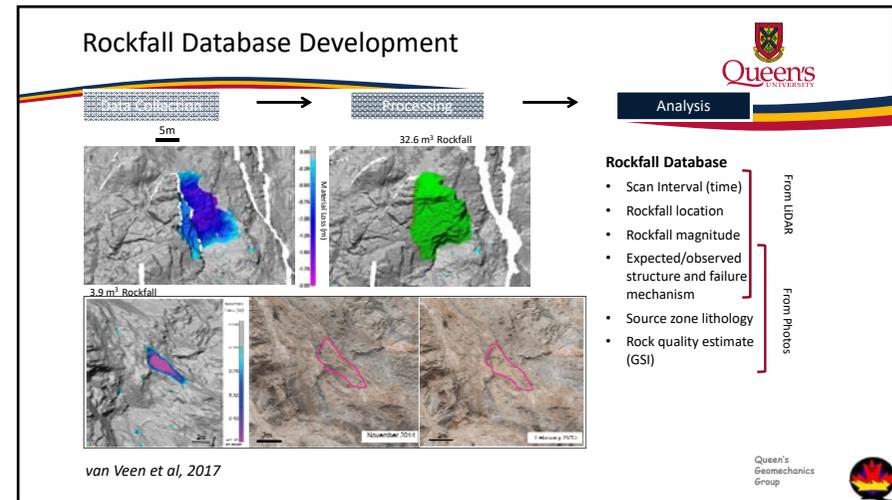
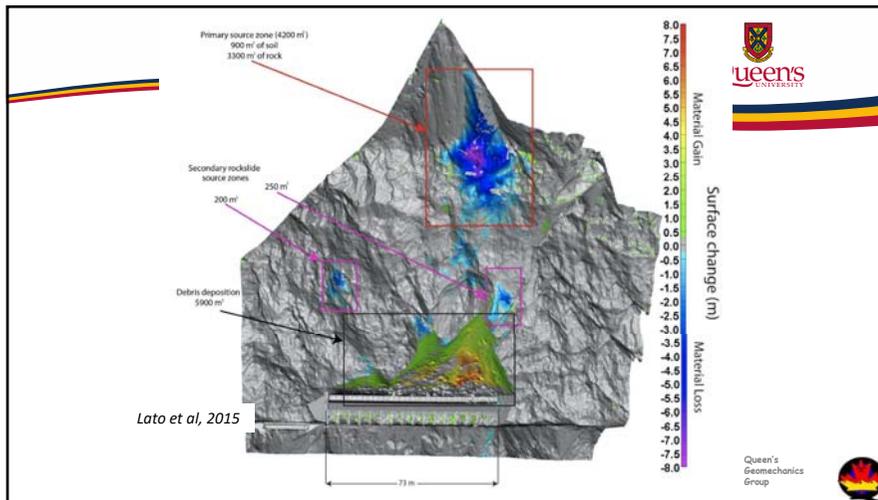
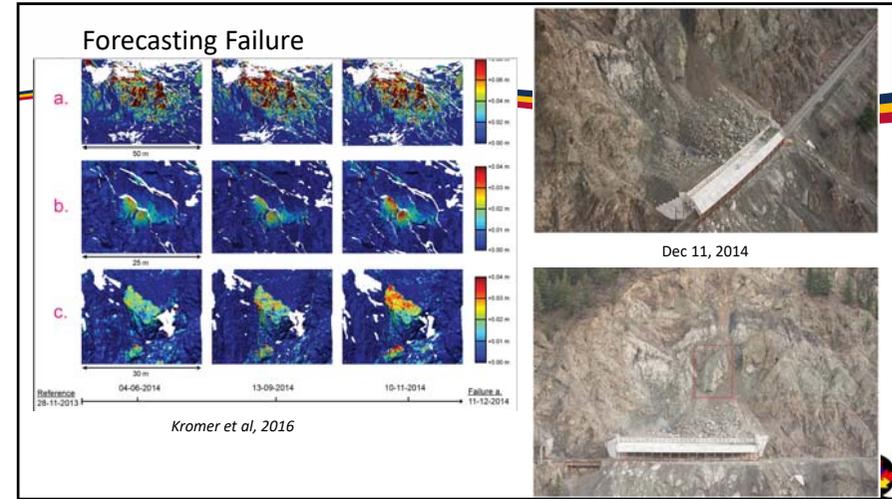
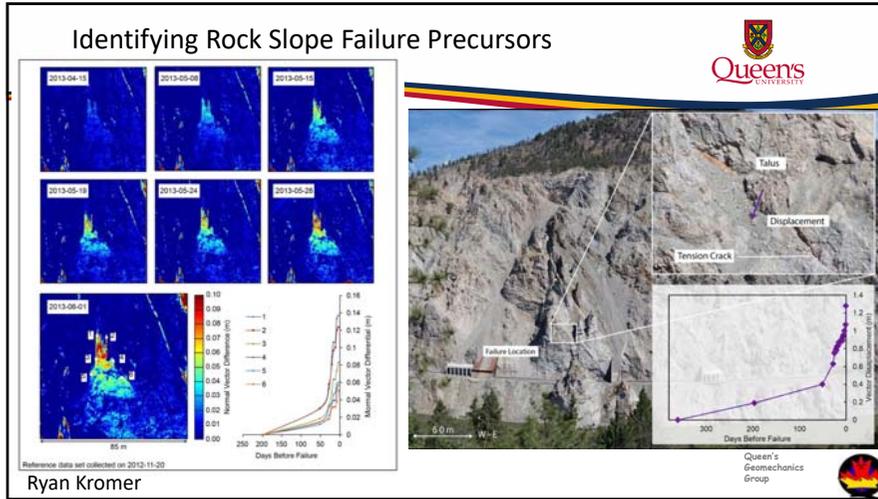
0.50
0.40
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0.00
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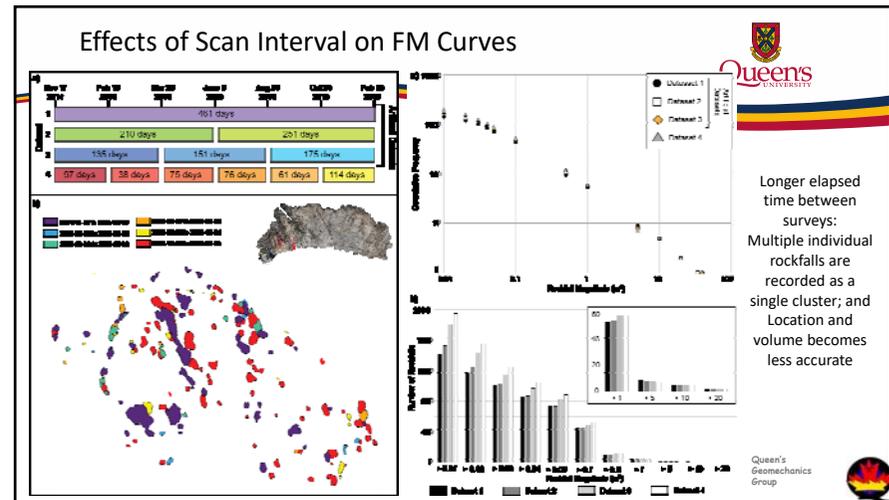
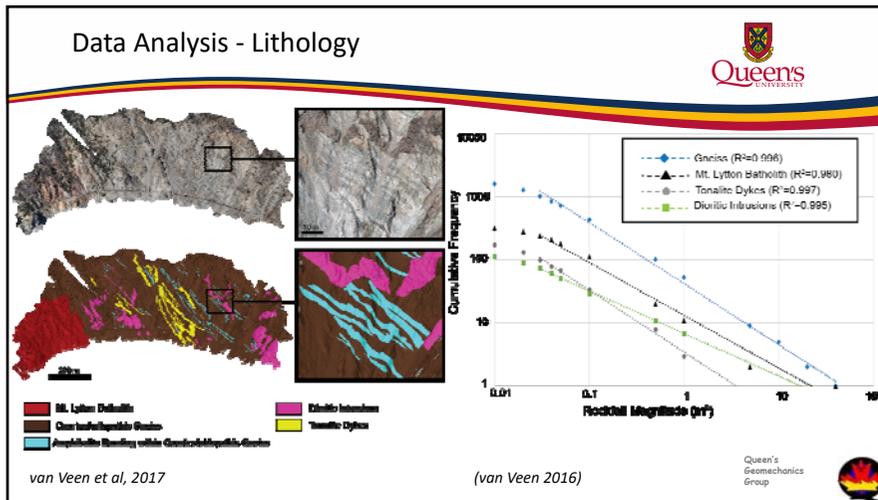
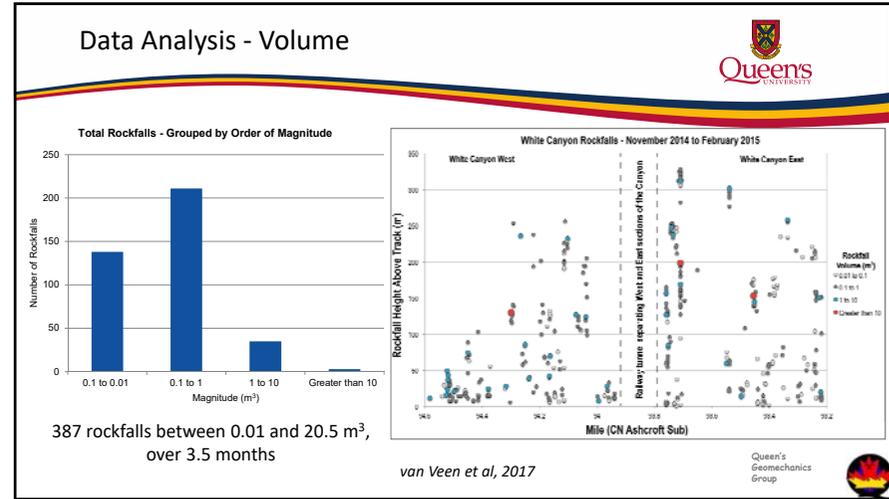
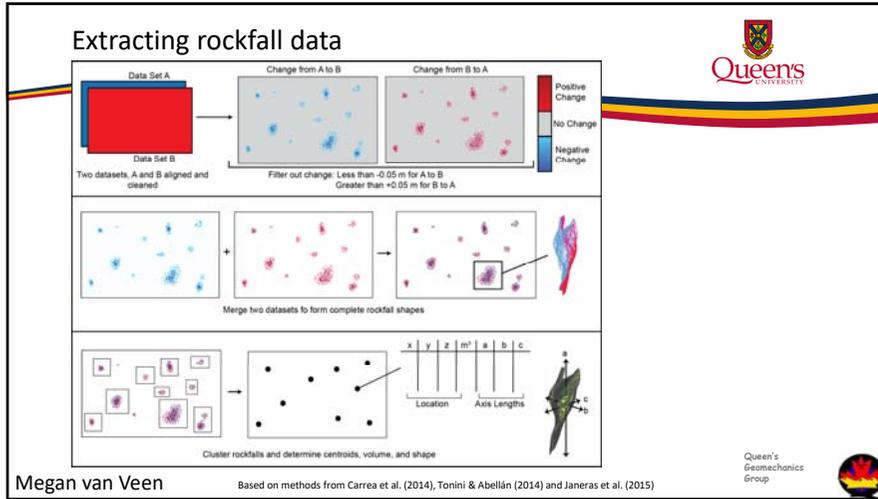
Matt Lato

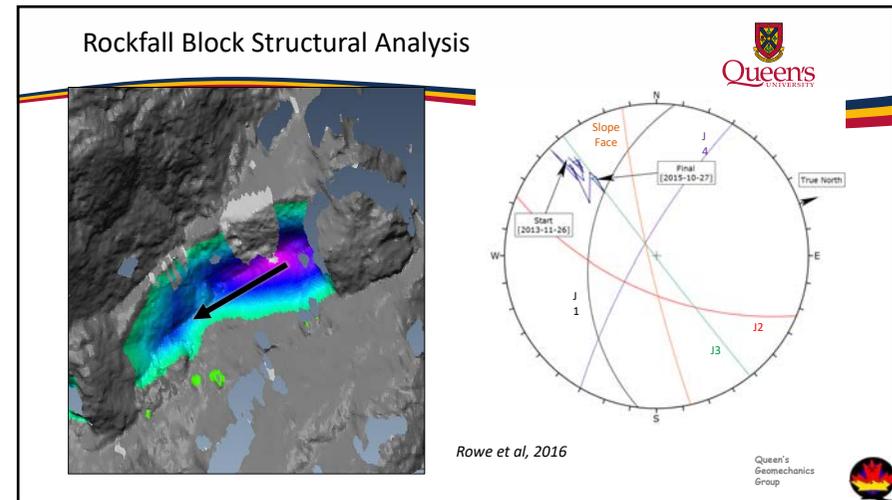
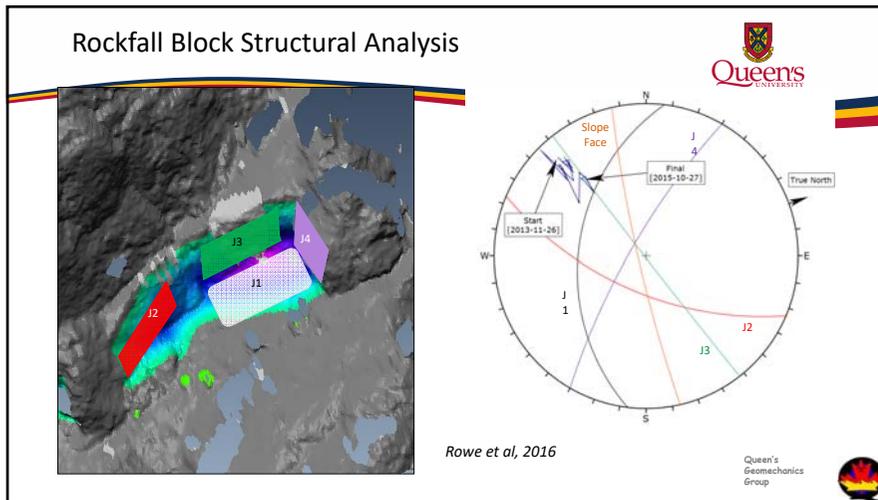
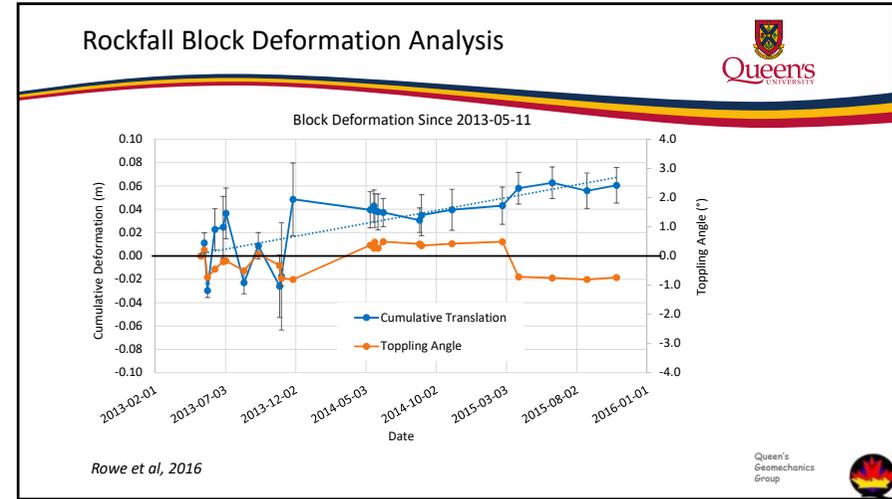
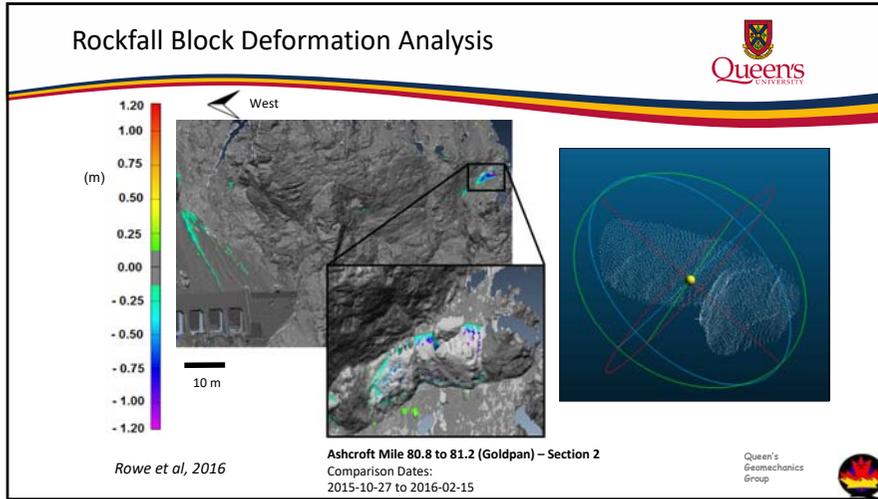
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Determining warning thresholds for different failure mechanisms

Planar Sliding
Hoek et al. 1974

Wedge Failure
Hoek et al. 1974

Toppling
Goodman et al. 1976

Rotational Failure

Overhang Failure

Emily Rowe

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Conceptual failure mechanism behaviour

Planar Sliding

Wedge Failure

Toppling

Rotational Failure

Overhang Failure

— Cumulative Translation
— Topping Angle

Rowe et al, 2016

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Modelling Rockfalls using Game Engines

- Fully 3D
- Built-in physics
 - NVIDIA PhysX Engine
 - Robust collision detection
 - Rigidbody dynamics
- Intuitive development environment
 - Pre-existing 3D coordinate system
 - Realistic visualization through lighting and texture
 - Modular and object-oriented
 - Fully scriptable (C# or JavaScript)
- Regularly updated
 - Freely available
 - Supported by large community of developers

Zac Sala

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Calibration of rockfall simulation via path analysis

18 m³ failure

Slide Detector Fence

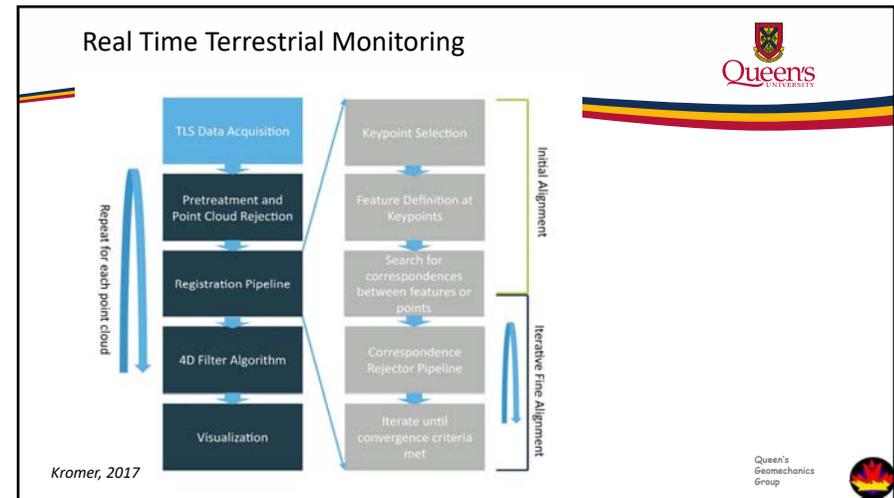
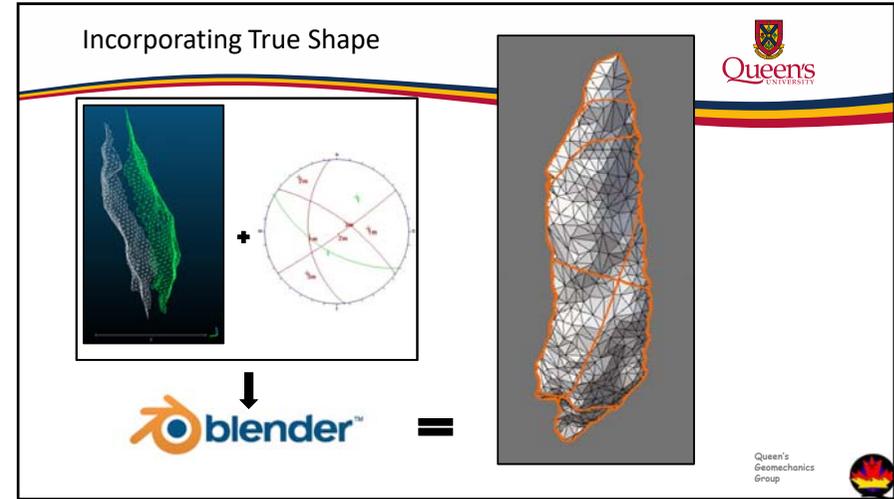
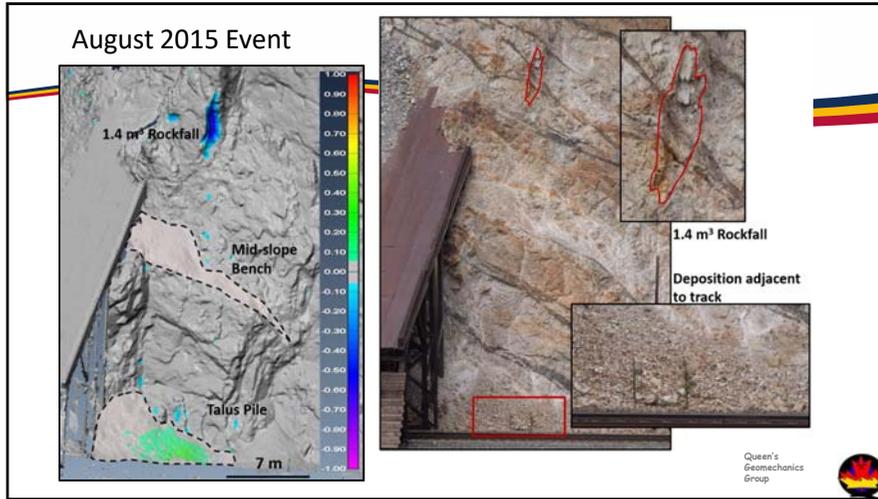
CN Rail

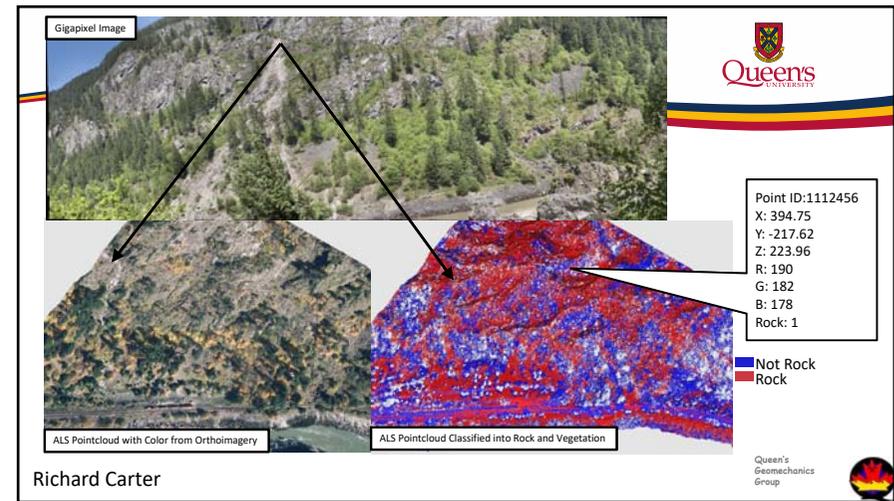
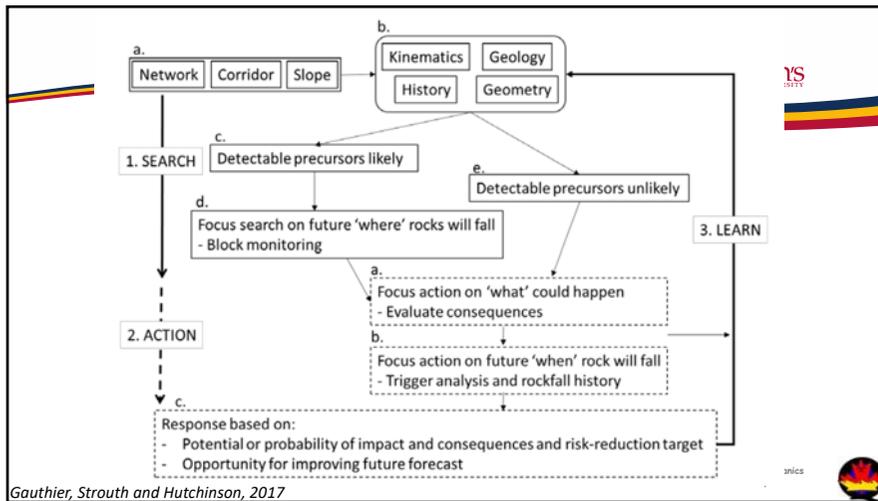
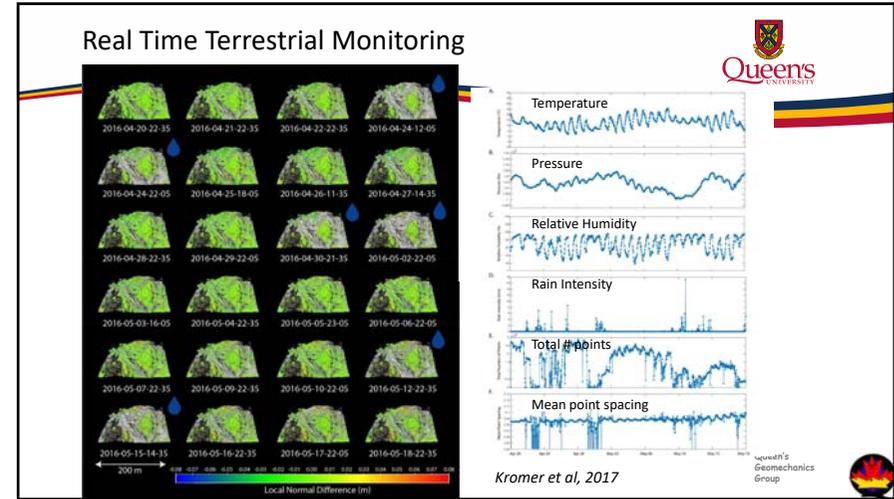
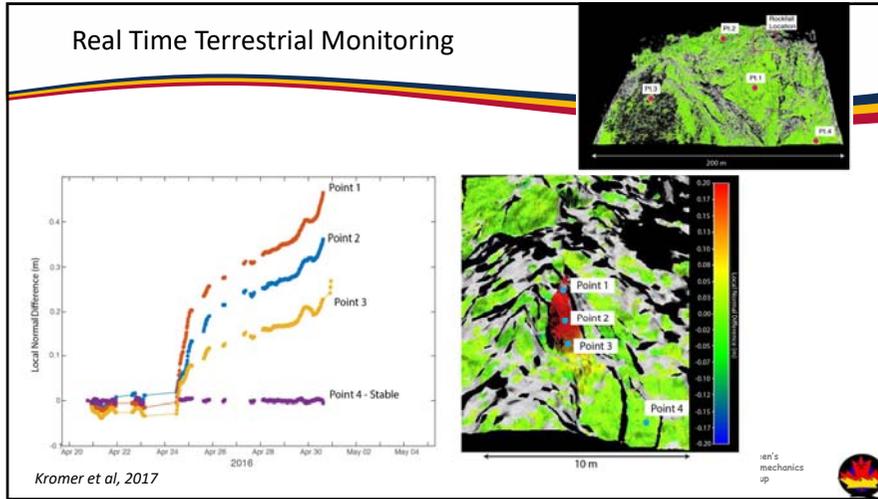
RockFall Protection Shed

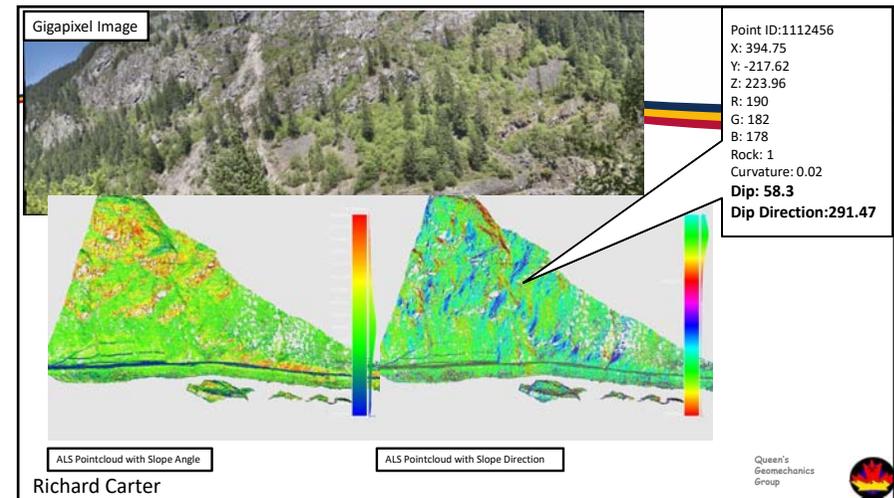
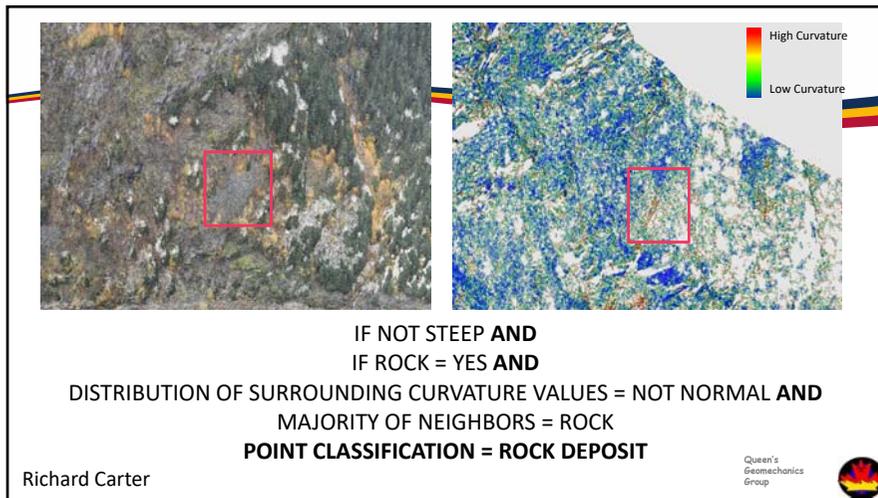
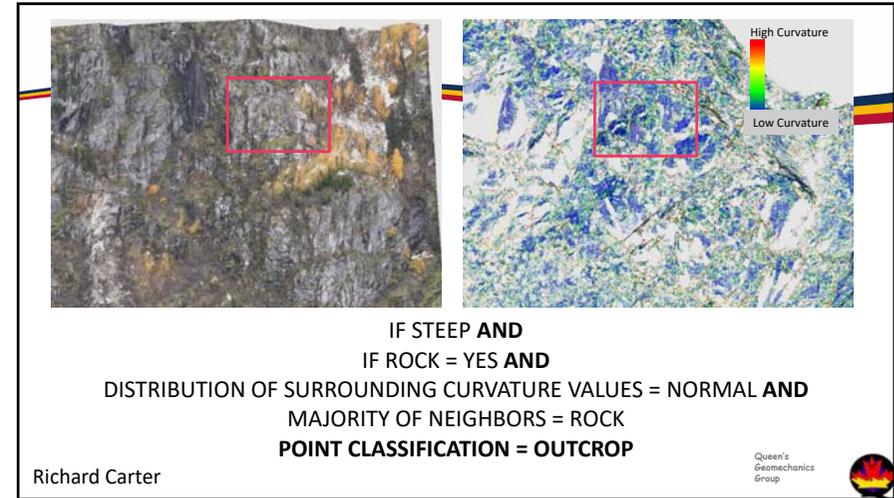
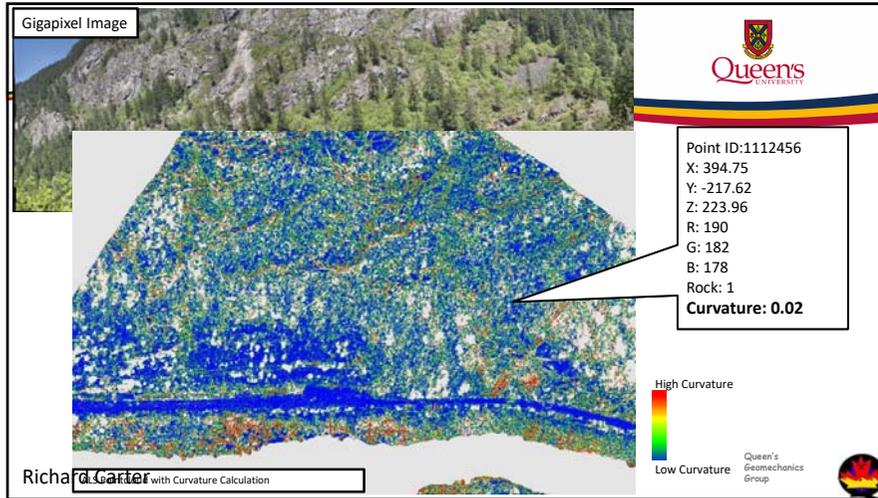
0 5 10 15 Meters

Ondercin et al, 2015

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Conclusions



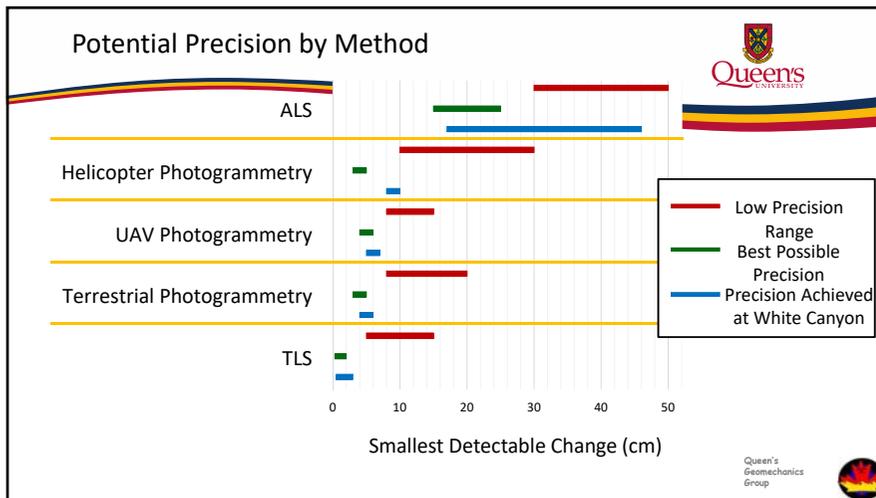
- Remotely sensed detailed 3-D geometrical models are superb data sets for slope stability analysis, particularly if:
 - Models taken from multiple vantage points are available,
 - Time sequential models can be compared.
- RS techniques are more versatile than ever before, due to:
 - High rate of acquisition of detailed data,
 - New techniques to build data sets, through intelligent and selective alignment processes,
 - Software packages readily available to work with data, and
 - Visualization tools to display the data easily.



Conclusions



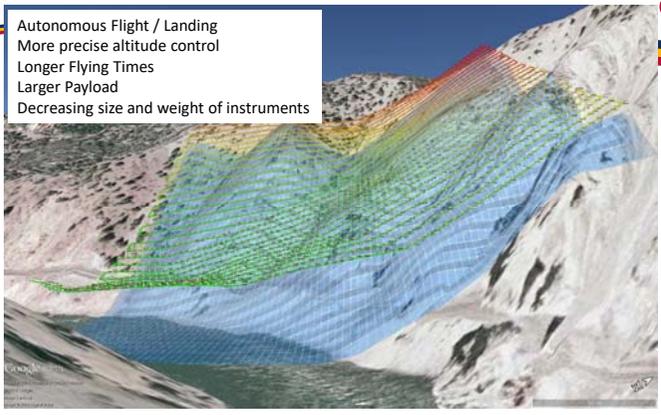
- Repeated scans of rock slopes allow:
 - Detection of very small, precursor changes, not sufficient to damage infrastructure, but as indicators of larger scale failure potential.
 - Detection of sub-cm scale deformation, permitting analysis of deformation rates over time, and type of movement whether accelerating, stick-slip, or steady state.
 - Forecast of impending rock slope failure.
 - Identification of rock slope failures at a wide range of volumes for analysis and for calibration data sets for new generation rockfall modelling.

Next steps – data collection



- Autonomous Flight / Landing
- More precise altitude control
- Longer Flying Times
- Larger Payload
- Decreasing size and weight of instruments




Next Steps



- Development of data processing methods to permit increasingly precise and accurate interpretation – underway by R. Kromer.
- Definition of appropriate methods, and frequency of scans, depending upon requirements: general review of rock slope instability or detailed geomorphological analysis – underway by A. Graham for rockfalls and D. Bonneau for debris channels.
- Expand change detection capabilities to larger scales, other forms of remote sensing, including aerial LiDAR – underway by R. Carter; and satellite based – underway by R. Hudson.
- Move towards pro-active rock slope risk management via monitoring and calibrated modelling – underway by Z. Sala.
- Detailed analysis of weather and climate impacts on frequency and magnitude of failure.

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3rd Virtual Geoscience Conference
23-24 August 2018, Kingston, Canada
Short Course August 22

Augmenting Geoscience Reality

www.virtualoutcrop.com/vgc2018

Thank you for your attention



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